Capturing and Animating Skin Deformation in Human Motion

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Figure 1: Capture and animation of the dynamic motion of the surface of the human body.

Abstract

During dynamic activities, the surface of the human body moves in many subtle but visually significant ways: bending, bulging, jiggling, and stretching. We present a technique for capturing and animating those motions using a commercial motion capture system and approximately 350 markers. Although the number of markers is significantly larger than that used in conventional motion capture, it is only a sparse representation of the true shape of the body. We supplement this sparse sample with a detailed, actorspecific surface model. The motion of the skin can then be computed by segmenting the markers into the motion of a set of rigid parts and a residual deformation (approximated first as a quadratic transformation and then with radial basis functions). We demonstrate the power of this approach by capturing flexing muscles, high frequency motions, and abrupt decelerations on several actors. We compare these results both to conventional motion capture and skinning and to synchronized video of the actors.

CR Categories: I.3.7 [Computer Graphics]: Three-Dimensional Graphics and Realism—Animation

Keywords: human animation, motion capture, skin deformation

1 Introduction

Optical motion capture has been used very successfully to create compelling human animations for movies and sports video games; however, it provides only a much simplified version of what we would see if we were to view a person actually performing those actions. The data contain an approximation of the motion of the

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skeleton but miss such subtle effects as the bulging of muscles and the jiggling of flesh. The current state of the art for whole body capture uses a set of 40-60 markers and reduces it to the rigid body motion of 15-22 segments. To the extent possible, the markers are placed on joint axes and bony landmarks so that they can more easily be used to approximate the motion of the skeleton. Biomechanical invariants are often used to reduce the number of markers to less than the number required to fully specify the orientation of each limb.

In this paper, we take a different approach to motion capture and use a very large set of markers (approximately 350) placed not on bony landmarks but on the muscular and fleshy parts of the body. Our goal is to obtain not only the motion of the skeleton but also the motion of the surface of the skin.

We accurately reconstruct the motion of the surface of the body by applying the three-dimensional trajectories for this dense marker set to a subject-specific polygonal model (Figure 1). The polygonal model is first optimized to fit the three-dimensional locations of the markers from a static pose. During the motion, the rigid body motion of the dense marker set is extracted and the remaining motion of the markers is used to compute local deformations of the polygonal model. The position of occluded markers is estimated from the locations of neighboring markers using a local model of the surface shape. The deformations of the marker set allow the muscle shapes in the polygonal model to grow and shrink and the fleshy areas to move dynamically.

To demonstrate the viability of this technique, we captured the motion of two subjects: a male football player (university-level offensive lineman) and a female professional belly dancer. Both subjects exhibited significant muscle and skin deformation when they performed dynamic activities. To evaluate the results, we compared motion captured with the dense marker set to synchronized video and to similar motions captured with a standard marker set and rendered using the same model and the skinning techniques available in commercial software.

2 Background

Data-driven approaches such as the one described in this paper are only one possible way to create an animation of the deformations

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